

壳体的非线性应变分量*

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摘 要

壳体的非线性应变分量是非线性壳体力学的基础, 在壳体的稳定以及各种大变形问题中须要用到它们. 由于壳体几何复杂, 在现有文献中, 还未见到较全面地表示此种非线性应变分量的一般公式, 现在导出六个用正交曲线坐标表示的包括线性与非线性部分的壳体应变分量的公式, 其中三个为拉伸应变分量, 另三个为剪切应变分量.

设 P 为壳体内一任意点, Q 为 P 的邻点, PQ 代表变形前长度为 ds 的微线元, $P'Q'$ 代表变形后同一线元, 其长度为 ds' . 各点的位置由下列正交曲线坐标表示:

$$P(\xi, \eta, \zeta), Q(\xi+d\xi, \eta+d\eta, \zeta+d\zeta)$$

$$P'(\xi', \eta', \zeta'), Q'(\xi'+d\xi', \eta'+d\eta', \zeta'+d\zeta')$$

l, m, n 为 ds 分别对与正交曲线坐标 ξ, η, ζ 在 P 点相切的直角坐标 x, y, z 的夹角的方向余弦;

l', m', n' 相应地为 ds' 分别对在 P' 点切于 ξ', η', ζ' 的直角坐标 x', y', z' 的夹角的方向余弦;

U, V, W 为位移 PP' 分别在 x, y, z 方向的投影;

A, B, C 为在 P 点将曲线坐标增量转为线性距离的拉梅 (Lamé) 系数.

于是, ds 在 x, y, z 方向的投影分别为:

$$l ds = A d\xi, m ds = B d\eta, n ds = C d\zeta \quad (1)$$

将上式平方后相加得:

$$(ds)^2 = (A d\xi)^2 + (B d\eta)^2 + (C d\zeta)^2 \quad (2)$$

P' 点的曲线坐标与 P 点的曲线坐标的关系由下式表示:

$$\left. \begin{aligned} \xi' &= \xi + \lambda \\ \eta' &= \eta + \mu \\ \zeta' &= \zeta + \gamma \end{aligned} \right\} \quad (3)$$

其中, λ, μ, γ 为 ξ, η 及 ζ 的函数, 即

$$\left. \begin{aligned} \lambda &= \lambda(\xi, \eta, \zeta) \\ \mu &= \mu(\xi, \eta, \zeta) \\ \gamma &= \gamma(\xi, \eta, \zeta) \end{aligned} \right\} \quad (4)$$

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故

$$\left. \begin{aligned} d\xi' &= d\xi + d\lambda = d\xi + \frac{\partial\lambda}{\partial\xi} d\xi + \frac{\partial\lambda}{\partial\eta} d\eta + \frac{\partial\lambda}{\partial\zeta} d\zeta \\ d\eta' &= d\eta + d\mu = d\eta + \frac{\partial\mu}{\partial\xi} d\xi + \frac{\partial\mu}{\partial\eta} d\eta + \frac{\partial\mu}{\partial\zeta} d\zeta \\ d\zeta' &= d\zeta + d\gamma = d\zeta + \frac{\partial\gamma}{\partial\xi} d\xi + \frac{\partial\gamma}{\partial\eta} d\eta + \frac{\partial\gamma}{\partial\zeta} d\zeta \end{aligned} \right\} \quad (5)$$

相应地, P' 点的拉梅系数 A', B', C' 与 P 点的拉梅系数的关系由下式表示:

$$\left. \begin{aligned} A' &= A + dA = A + \frac{\partial A}{\partial\xi} \lambda + \frac{\partial A}{\partial\eta} \mu + \frac{\partial A}{\partial\zeta} \gamma \\ B' &= B + dB = B + \frac{\partial B}{\partial\xi} \lambda + \frac{\partial B}{\partial\eta} \mu + \frac{\partial B}{\partial\zeta} \gamma \\ C' &= C + dC = C + \frac{\partial C}{\partial\xi} \lambda + \frac{\partial C}{\partial\eta} \mu + \frac{\partial C}{\partial\zeta} \gamma \end{aligned} \right\} \quad (6)$$

于是, 变形后的线元 ds' 在 P' 点与正交曲线坐标 ξ' 相切的直角坐标 x' 方向的投影为

$$\begin{aligned} l'ds' &= A'd\xi' = \left(A + \frac{\partial A}{\partial\xi} \lambda + \frac{\partial A}{\partial\eta} \mu + \frac{\partial A}{\partial\zeta} \gamma \right) \left(d\xi + \frac{\partial\lambda}{\partial\xi} d\xi + \frac{\partial\lambda}{\partial\eta} d\eta + \frac{\partial\lambda}{\partial\zeta} d\zeta \right) \\ &= Ad\xi + \frac{\partial A}{\partial\xi} \lambda d\xi + \frac{\partial A}{\partial\eta} \mu d\xi + \frac{\partial A}{\partial\zeta} \gamma d\xi + \frac{\partial\lambda}{\partial\xi} Ad\xi \\ &\quad + \frac{\partial\lambda}{\partial\eta} Ad\eta + \frac{\partial A}{\partial\zeta} Ad\zeta + \dots \end{aligned} \quad (7)$$

注意上式括号内导数与导数的乘积项属于三级微量, 可以省略.

沿 x, y, z 轴方向的位移分别为:

$$U = A\lambda, \quad V = B\mu, \quad W = C\gamma \quad (8)$$

经过下列简单变换:

$$\begin{aligned} \left(\frac{\partial A}{\partial\xi} \lambda + \frac{\partial\lambda}{\partial\xi} A \right) d\xi &= \frac{1}{A} \frac{\partial(A\lambda)}{\partial\xi} Ad\xi = \frac{1}{A} \frac{\partial U}{\partial\xi} lds \\ \frac{\partial A}{\partial\eta} \mu d\xi &= \frac{(B\mu)}{AB} \frac{\partial A}{\partial\eta} Ad\xi = \frac{V}{AB} \frac{\partial A}{\partial\eta} lds \\ \frac{\partial A}{\partial\zeta} \gamma d\xi &= \frac{(C\gamma)}{AC} \frac{\partial A}{\partial\zeta} Ad\xi = \frac{W}{AC} \frac{\partial A}{\partial\zeta} lds \\ \frac{\partial\lambda}{\partial\eta} Ad\eta &= \frac{A}{B} \frac{\partial}{\partial\eta} \left(\frac{A\lambda}{A} \right) B d\eta = \frac{A}{B} \frac{\partial}{\partial\eta} \left(\frac{U}{A} \right) mds \\ \frac{\partial\lambda}{\partial\zeta} Ad\zeta &= \frac{A}{C} \frac{\partial}{\partial\zeta} \left(\frac{A\lambda}{A} \right) C d\zeta = \frac{A}{C} \frac{\partial}{\partial\zeta} \left(\frac{U}{A} \right) nds \end{aligned}$$

式(7)成为

$$l'ds' = \left(1 + \frac{1}{A} \frac{\partial U}{\partial\xi} + \frac{V}{AB} \frac{\partial A}{\partial\eta} + \frac{W}{AC} \frac{\partial A}{\partial\zeta} \right) lds$$

$$+\frac{A}{B} \frac{\partial}{\partial \eta} \left(\frac{U}{A} \right) m ds + \frac{A}{C} \frac{\partial}{\partial \xi} \left(\frac{U}{A} \right) n ds \quad (9a)$$

同样地

$$m' ds' = \frac{B}{A} \frac{\partial}{\partial \xi} \left(\frac{V}{B} \right) l ds + \left(1 + \frac{1}{B} \frac{\partial V}{\partial \eta} + \frac{W}{BC} \frac{\partial B}{\partial \xi} + \frac{U}{AB} \frac{\partial B}{\partial \xi} \right) m ds + \frac{B}{C} \frac{\partial}{\partial \xi} \left(\frac{V}{B} \right) n ds \quad (9b)$$

$$n' ds' = \frac{C}{A} \frac{\partial}{\partial \xi} \left(\frac{W}{C} \right) l ds + \frac{C}{B} \frac{\partial}{\partial \eta} \left(\frac{W}{C} \right) m ds + \left(1 + \frac{1}{C} \frac{\partial W}{\partial \xi} + \frac{U}{AC} \frac{\partial C}{\partial \xi} + \frac{V}{BC} \frac{\partial C}{\partial \eta} \right) n ds \quad (9c)$$

设 ϵ 为线元 ds 的应变,

$$\epsilon = \frac{ds' - ds}{ds} \quad ds' = (1 + \epsilon) ds \quad (10)$$

而

$$(ds')^2 = (l' ds')^2 + (m' ds')^2 + (n' ds')^2$$

将(9)与(10)代入上式,略去微量 ϵ^2 ,

$$1 + 2\epsilon = \left[\left(1 + \frac{1}{A} \frac{\partial U}{\partial \xi} + \frac{V}{AB} \frac{\partial A}{\partial \eta} + \frac{W}{AC} \frac{\partial A}{\partial \xi} \right) l + \frac{A}{B} \frac{\partial}{\partial \eta} \left(\frac{U}{A} \right) m + \frac{A}{C} \frac{\partial}{\partial \xi} \left(\frac{U}{A} \right) n \right]^2 + \left[\frac{B}{A} \frac{\partial}{\partial \xi} \left(\frac{V}{B} \right) l + \left(1 + \frac{1}{B} \frac{\partial V}{\partial \eta} + \frac{W}{BC} \frac{\partial B}{\partial \xi} + \frac{U}{AB} \frac{\partial B}{\partial \xi} \right) m + \frac{B}{C} \frac{\partial}{\partial \xi} \left(\frac{V}{B} \right) n \right]^2 + \left[\frac{C}{A} \frac{\partial}{\partial \xi} \left(\frac{W}{C} \right) l + \frac{C}{B} \frac{\partial}{\partial \eta} \left(\frac{W}{C} \right) m + \left(1 + \frac{1}{C} \frac{\partial W}{\partial \xi} + \frac{U}{AC} \frac{\partial C}{\partial \xi} + \frac{V}{BC} \frac{\partial C}{\partial \eta} \right) n \right]^2 \quad (11)$$

将式(11)展开,得

$$\epsilon = \epsilon_l l^2 + \epsilon_m m^2 + \epsilon_n n^2 + \gamma_{lm} lm + \gamma_{ln} ln + \gamma_{mn} mn$$

其中

$$\epsilon_l = \frac{1}{A} \frac{\partial U}{\partial \xi} + \frac{V}{AB} \frac{\partial A}{\partial \eta} + \frac{W}{AC} \frac{\partial A}{\partial \xi} + \frac{1}{2} \left\{ \left[\frac{1}{A} \frac{\partial U}{\partial \xi} + \frac{V}{AB} \frac{\partial A}{\partial \eta} + \frac{W}{AC} \frac{\partial A}{\partial \xi} \right]^2 + \left[\frac{B}{A} \frac{\partial}{\partial \xi} \left(\frac{V}{B} \right) \right]^2 + \left[\frac{C}{A} \frac{\partial}{\partial \xi} \left(\frac{W}{C} \right) \right]^2 \right\} \quad (12a)$$

$$\epsilon_m = \frac{1}{B} \frac{\partial V}{\partial \eta} + \frac{W}{BC} \frac{\partial B}{\partial \xi} + \frac{U}{AB} \frac{\partial B}{\partial \xi} + \frac{1}{2} \left\{ \left[\frac{A}{B} \frac{\partial}{\partial \eta} \left(\frac{U}{A} \right) \right]^2 + \left[\frac{1}{B} \frac{\partial V}{\partial \eta} + \frac{W}{BC} \frac{\partial B}{\partial \xi} + \frac{U}{AB} \frac{\partial B}{\partial \xi} \right]^2 + \left[\frac{C}{B} \frac{\partial}{\partial \eta} \left(\frac{W}{C} \right) \right]^2 \right\} \quad (12b)$$

$$\epsilon_n = \frac{1}{C} \frac{\partial W}{\partial \xi} + \frac{U}{AC} \frac{\partial C}{\partial \xi} + \frac{V}{BC} \frac{\partial C}{\partial \eta} + \frac{1}{2} \left\{ \left[\frac{A}{C} \frac{\partial}{\partial \xi} \left(\frac{U}{A} \right) \right]^2 \right\}$$

$$+\left[\frac{B}{C}\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)\right]^2+\left[\frac{1}{C}\frac{\partial W}{\partial\xi}+\frac{U}{AC}\frac{\partial C}{\partial\xi}+\frac{V}{BC}\frac{\partial C}{\partial\eta}\right]^2\} \quad (12c)$$

$$\begin{aligned} \gamma_{\xi\eta} = & \frac{A}{B}\frac{\partial}{\partial\eta}\left(\frac{U}{A}\right)+\frac{B}{A}\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)+\frac{1}{B}\frac{\partial}{\partial\eta}\left(\frac{U}{A}\right)\left[\frac{\partial U}{\partial\xi}+\frac{V}{B}\frac{\partial A}{\partial\eta}\right. \\ & \left.+\frac{W}{C}\frac{\partial A}{\partial\xi}\right]+\frac{1}{A}\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)\left[\frac{\partial V}{\partial\eta}+\frac{W}{C}\frac{\partial B}{\partial\xi}\right. \\ & \left.+\frac{U}{A}\frac{\partial B}{\partial\xi}\right]+\frac{C^2}{AB}\frac{\partial}{\partial\xi}\left(\frac{W}{C}\right)\frac{\partial}{\partial\eta}\left(\frac{W}{C}\right) \end{aligned} \quad (12d)$$

$$\begin{aligned} \gamma_{\eta\xi} = & \frac{B}{C}\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)+\frac{C}{B}\frac{\partial}{\partial\eta}\left(\frac{W}{C}\right)+\frac{A^2}{BC}\frac{\partial}{\partial\eta}\left(\frac{U}{A}\right)\frac{\partial}{\partial\xi}\left(\frac{U}{A}\right) \\ & +\frac{1}{C}\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)\left[\frac{\partial V}{\partial\eta}+\frac{W}{C}\frac{\partial B}{\partial\xi}+\frac{U}{A}\frac{\partial B}{\partial\xi}\right] \\ & +\frac{1}{B}\frac{\partial}{\partial\eta}\left(\frac{W}{C}\right)\left[\frac{\partial W}{\partial\xi}+\frac{U}{A}\frac{\partial C}{\partial\xi}+\frac{V}{B}\frac{\partial C}{\partial\eta}\right] \end{aligned} \quad (12e)$$

$$\begin{aligned} \gamma_{\xi\xi} = & \frac{C}{A}\frac{\partial}{\partial\xi}\left(\frac{W}{C}\right)+\frac{A}{C}\frac{\partial}{\partial\xi}\left(\frac{U}{A}\right)+\frac{1}{C}\frac{\partial}{\partial\xi}\left(\frac{U}{A}\right)\left[\frac{\partial U}{\partial\xi}+\frac{V}{B}\frac{\partial A}{\partial\eta}+\frac{W}{C}\frac{\partial A}{\partial\xi}\right] \\ & +\frac{B^2}{AC}\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)\frac{\partial}{\partial\xi}\left(\frac{V}{B}\right)+\frac{1}{A}\frac{\partial}{\partial\xi}\left(\frac{W}{C}\right)\left[\frac{\partial W}{\partial\xi}+\frac{U}{A}\frac{\partial C}{\partial\xi}+\frac{V}{B}\frac{\partial C}{\partial\eta}\right] \end{aligned} \quad (12f)$$

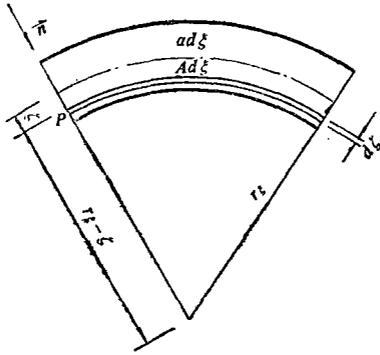


图 1

上六式为弹塑性体发生位移后在 P 点 (ξ, η, ζ) 的六个应变分量, 前三者为拉伸应变分量, 后三者为剪切应变分量, 每一分量包括线性与非线性两部分。

现将此等分量用壳体中面系数表示。如图 1 所示, 单位法向矢量指向曲面坐标 ζ 的正方向。

$$\left. \begin{aligned} A &= \alpha \left(1 - \frac{\zeta}{r_\xi} \right) \\ B &= \beta \left(1 - \frac{\zeta}{r_\eta} \right) \\ C &= 1 \end{aligned} \right\} \quad (13)$$

用门拉底—柯打齐 (Mainardi-Codazzi) 关系

$$\left. \begin{aligned} \frac{1}{r_\eta} \frac{\partial \alpha}{\partial \eta} &= \frac{\partial}{\partial \eta} \left(\frac{\alpha}{r_\xi} \right) \\ \frac{1}{r_\xi} \frac{\partial \beta}{\partial \xi} &= \frac{\partial}{\partial \xi} \left(\frac{\beta}{r_\eta} \right) \end{aligned} \right\} \quad (14)$$

知有下列关系的存在,

$$\left. \begin{aligned} \frac{\partial}{\partial \eta} \left[\alpha \left(1 - \frac{\xi}{r_i} \right) \right] &= \frac{\partial \alpha}{\partial \eta} \left(1 - \frac{\xi}{r_i} \right) \\ \frac{\partial}{\partial \xi} \left[\beta \left(1 - \frac{\xi}{r_n} \right) \right] &= \frac{\partial \beta}{\partial \xi} \left(1 - \frac{\xi}{r_n} \right) \end{aligned} \right\} \quad (15)$$

将(13)代入(12), 并在需要时引用(15)得:

$$\begin{aligned} \epsilon_t &= \frac{1}{\alpha \left(1 - \frac{\xi}{r_i} \right)} \left(\frac{\partial U}{\partial \xi} + \frac{V}{\beta} \frac{\partial \alpha}{\partial \eta} - \alpha \frac{W}{r_i} \right) \\ &+ \frac{1}{2 \left[\alpha \left(1 - \frac{\xi}{r_i} \right) \right]^2} \left\{ \left[\frac{\partial U}{\partial \xi} + \frac{V}{\beta} \frac{\partial \alpha}{\partial \eta} - \alpha \frac{W}{r_i} \right]^2 \right. \\ &\left. + \left[\beta \left(1 - \frac{\xi}{r_n} \right) \frac{\partial}{\partial \xi} \left[\frac{V}{\beta \left(1 - \frac{\xi}{r_n} \right)} \right] \right]^2 + \left[\frac{\partial W}{\partial \xi} \right]^2 \right\} \end{aligned} \quad (16a)$$

$$\begin{aligned} \epsilon_n &= \frac{1}{\beta \left(1 - \frac{\xi}{r_n} \right)} \left(\frac{\partial V}{\partial \eta} - \beta \frac{W}{r_n} + \frac{U}{\alpha} \frac{\partial \beta}{\partial \xi} \right) \\ &+ \frac{1}{2 \left[\beta \left(1 - \frac{\xi}{r_n} \right) \right]^2} \left\{ \left[\alpha \left(1 - \frac{\xi}{r_i} \right) \frac{\partial}{\partial \eta} \left[\frac{U}{\alpha \left(1 - \frac{\xi}{r_i} \right)} \right] \right]^2 \right. \\ &\left. + \left[\frac{\partial V}{\partial \eta} - \beta \frac{W}{r_n} + \frac{U}{\alpha} \frac{\partial \beta}{\partial \xi} \right]^2 + \left[\frac{\partial W}{\partial \eta} \right]^2 \right\} \end{aligned} \quad (16b)$$

$$\begin{aligned} \epsilon_c &= \frac{\partial W}{\partial \xi} + \frac{1}{2} \left\{ \left[\alpha \left(1 - \frac{\xi}{r_i} \right) \frac{\partial}{\partial \xi} \left[\frac{U}{\alpha \left(1 - \frac{\xi}{r_i} \right)} \right] \right]^2 \right. \\ &\left. + \left[\beta \left(1 - \frac{\xi}{r_n} \right) \frac{\partial}{\partial \xi} \left[\frac{V}{\beta \left(1 - \frac{\xi}{r_n} \right)} \right] \right]^2 + \left[\frac{\partial W}{\partial \xi} \right]^2 \right\} \end{aligned} \quad (16c)$$

$$\begin{aligned} \gamma_{in} &= \frac{\alpha \left(1 - \frac{\xi}{r_i} \right)}{\beta \left(1 - \frac{\xi}{r_n} \right)} \frac{\partial}{\partial \eta} \left[\frac{U}{\alpha \left(1 - \frac{\xi}{r_i} \right)} \right] + \frac{\beta \left(1 - \frac{\xi}{r_n} \right)}{\alpha \left(1 - \frac{\xi}{r_i} \right)} \frac{\partial}{\partial \xi} \left[\frac{V}{\beta \left(1 - \frac{\xi}{r_n} \right)} \right] \\ &+ \frac{1}{\beta \left(1 - \frac{\xi}{r_n} \right)} \frac{\partial}{\partial \eta} \left[\frac{U}{\alpha \left(1 - \frac{\xi}{r_i} \right)} \right] \cdot \left[\frac{\partial U}{\partial \xi} + \frac{V}{\beta} \frac{\partial \alpha}{\partial \eta} - \alpha \frac{W}{r_i} \right] \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{\alpha \left(1 - \frac{\xi}{r_i}\right)} \frac{\partial}{\partial \xi} \left] \frac{V}{\beta \left(1 - \frac{\xi}{r_n}\right)} \right] \cdot \left[\frac{\partial V}{\partial \eta} - \beta \frac{W}{r_n} + \frac{U}{\alpha} \frac{\partial \beta}{\partial \xi} \right] \\
& + \frac{1}{\alpha \beta \left(1 - \frac{\xi}{r_i}\right) \left(1 - \frac{\xi}{r_n}\right)} \frac{\partial W}{\partial \xi} \frac{\partial W}{\partial \eta} \tag{16d}
\end{aligned}$$

$$\begin{aligned}
\gamma_{\eta i} = & \left(1 - \frac{\xi}{r_n}\right) \frac{\partial}{\partial \xi} \left(\frac{V}{1 - \frac{\xi}{r_n}}\right) + \frac{1}{\beta \left(1 - \frac{\xi}{r_n}\right)} \frac{\partial W}{\partial \eta} \\
& + \frac{\alpha \left(1 - \frac{\xi}{r_i}\right)^2}{\beta \left(1 - \frac{\xi}{r_n}\right)} \frac{\partial}{\partial \xi} \left(\frac{U}{1 - \frac{\xi}{r_i}}\right) \frac{\partial}{\partial \eta} \left[\frac{U}{\alpha \left(1 - \frac{\xi}{r_i}\right)}\right] \\
& + \frac{1}{\beta} \frac{\partial}{\partial \xi} \left(\frac{V}{1 - \frac{\xi}{r_n}}\right) \cdot \left[\frac{\partial V}{\partial \eta} - \beta \frac{W}{r_n} + \frac{U}{\alpha} \frac{\partial \beta}{\partial \xi} \right] \\
& + \frac{1}{\beta \left(1 - \frac{\xi}{r_n}\right)} \frac{\partial W}{\partial \eta} \frac{\partial W}{\partial \xi} \tag{16e}
\end{aligned}$$

$$\begin{aligned}
\gamma_{i \xi} = & \frac{1}{\alpha \left(1 - \frac{\xi}{r_i}\right)} \frac{\partial W}{\partial \xi} + \left(1 - \frac{\xi}{r_i}\right) \frac{\partial}{\partial \xi} \left(\frac{U}{1 - \frac{\xi}{r_i}}\right) \\
& + \frac{1}{\alpha} \frac{\partial}{\partial \xi} \left(\frac{U}{1 - \frac{\xi}{r_i}}\right) \cdot \left[\frac{\partial U}{\partial \xi} + \frac{V}{\beta} \frac{\partial \alpha}{\partial \eta} - \alpha \frac{W}{r_i} \right] \\
& + \frac{\beta \left(1 - \frac{\xi}{r_n}\right)^2}{\alpha \left(1 - \frac{\xi}{r_i}\right)} \frac{\partial}{\partial \xi} \left(\frac{V}{1 - \frac{\xi}{r_n}}\right) \frac{\partial}{\partial \xi} \left[\frac{V}{\beta \left(1 - \frac{\xi}{r_i}\right)}\right] \\
& + \frac{1}{\alpha \left(1 - \frac{\xi}{r_i}\right)} \frac{\partial W}{\partial \xi} \frac{\partial W}{\partial \xi} \tag{16f}
\end{aligned}$$

为了验证式(16)的正确, 使

$$\xi = x, \quad \eta = y, \quad \zeta = z$$

$$\alpha = \beta = 1, \quad r_i = r_n = \infty$$

我们得以下六个为众所熟知的表示板的非线性应变分量的公式:

$$\left. \begin{aligned}
 \epsilon_x &= \frac{\partial U}{\partial x} + \frac{1}{2} \left[\left(\frac{\partial U}{\partial x} \right)^2 + \left(\frac{\partial V}{\partial x} \right)^2 + \left(\frac{\partial W}{\partial x} \right)^2 \right] \\
 \epsilon_y &= \frac{\partial V}{\partial y} + \frac{1}{2} \left[\left(\frac{\partial U}{\partial y} \right)^2 + \left(\frac{\partial V}{\partial y} \right)^2 + \left(\frac{\partial W}{\partial y} \right)^2 \right] \\
 \epsilon_z &= \frac{\partial W}{\partial z} + \frac{1}{2} \left[\left(\frac{\partial U}{\partial z} \right)^2 + \left(\frac{\partial V}{\partial z} \right)^2 + \left(\frac{\partial W}{\partial z} \right)^2 \right] \\
 \gamma_{xy} &= \frac{\partial U}{\partial y} + \frac{\partial V}{\partial x} + \frac{\partial U}{\partial x} \frac{\partial U}{\partial y} + \frac{\partial V}{\partial x} \frac{\partial V}{\partial y} + \frac{\partial W}{\partial x} \frac{\partial W}{\partial y} \\
 \gamma_{yz} &= \frac{\partial V}{\partial z} + \frac{\partial W}{\partial y} + \frac{\partial U}{\partial y} \frac{\partial U}{\partial z} + \frac{\partial V}{\partial y} \frac{\partial V}{\partial z} + \frac{\partial W}{\partial y} \frac{\partial W}{\partial z} \\
 \gamma_{zx} &= \frac{\partial W}{\partial x} + \frac{\partial U}{\partial z} + \frac{\partial U}{\partial z} \frac{\partial U}{\partial x} + \frac{\partial V}{\partial z} \frac{\partial V}{\partial x} + \frac{\partial W}{\partial z} \frac{\partial W}{\partial x}
 \end{aligned} \right\} \quad (17a-f)$$

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The Nonlinear Strain Components of Thin Shells

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Abstract

The nonlinear strain components of shells are the foundations of the nonlinear shell mechanics. They are used in the stability and various large deformation analyses of shells. Because of the complication of shell geometry we have not seen the general formulae of nonlinear strain components of shells in the existing references. Here we present a set of formulae including linear and nonlinear strain components of shells with orthogonal curvilinear coordinates. Three of them are tensile, the others are shear strain components.